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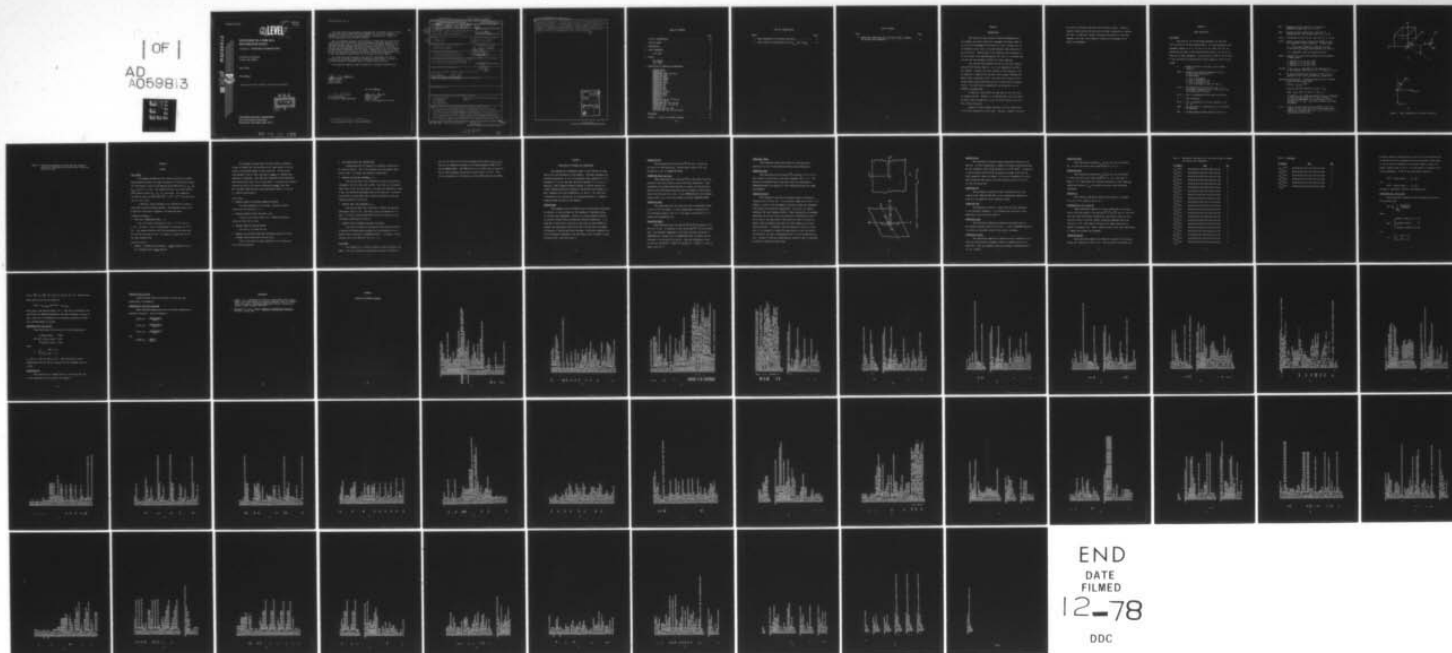
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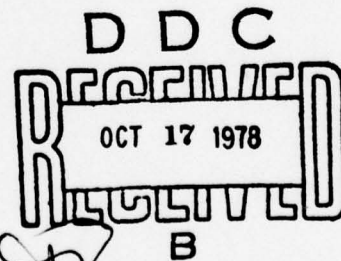
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University of Arizona
Tucson, AZ 85724

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Final Report

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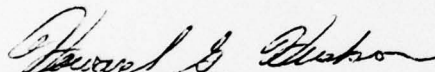


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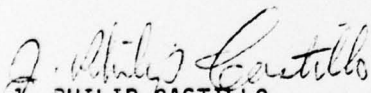
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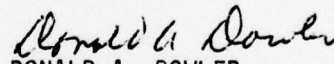
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Rectangular Cavity Dyadic Green's Functions for Rectangular Small Aperture Cavity Wire Scatterer Shielding Effects			
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In this work, the problem of determining the currents excited on a wire enclosed within a rectangular cavity is considered. The wire and cavity interior are excited by electromagnetic sources exterior to the cavity which couple to the cavity interior through a small aperture in the cavity wall. It is assumed that the wire is thin, straight and oriented perpendicular to one of the cavity walls. An integral equation is formulated for the problem in the frequency domain using equivalent dipole moments to approximate the			

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effects of the aperture. This integral equation is then solved numerically by the method of moments. The dyadic Green's functions for this problem are difficult to compute numerically; consequently, extensive numerical analysis is necessary to render the solution tractable. Sample numerical results are presented for representative configurations of cavity, wire and aperture, and suggestions for future extensions of this work are discussed.



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CHAPTER 1

INTRODUCTION

This report has been written to provide documentation to the computer code which numerically implements the theory found in [1] for the electromagnetic excitation of a thin, straight wire in a rectangular cavity which is excited through a small aperture in the cavity wall. Because many of the equations and discussions in [1] are crucial to an understanding of this code, it is assumed that the user has that document available for ready reference.

This code has been prepared for use on a CDC 6400 computer using the RUN fortran compiler. It is also compatible with CDC's FTN compiler. However, for later versions of this compiler it may be necessary to suppress the non-fatal error message "ARGUMENT TOO SMALL" which is detected in EXP. This error will naturally occur during normal program execution and has no effect upon the program output. This error can be suppressed by an appropriate call to SYSTEMC in program START.

In addition, every effort has been made to write the code in standard fortran. However, it is expected that a few minor modifications might be needed for its use on non-CDC machines and with other fortran compilers.

Chapter 2 of this document provides a list and description of all input parameters for this code. Similarly, chapter 3 outlines

the various information which the code returns as output. These two chapters should provide the user with the needed information to operate the code. In addition, chapter 4 discusses the function of each sub-program in the code, and a complete listing of all programs can be found in the appendix.

CHAPTER 2

INPUT PARAMETERS

File INPUT

Note that all of the following parameters are read from the file INPUT in the main program START. All input parameters that represent lengths (A, B, C, XC, YC, R, ZL, ZU, LBDA, XPP, YPP, RA, DELFIX) may be input in any system of units desired, so long as the same unit is used throughout. Also note that if LBDA is set to unity, it has the effect of normalizing all other lengths in units of wavelength.

- N -- Number of pulses to be used in wire current expansion
- IGRD -- Integer which indicates connection of wire to one or both cavity walls.
 If IGRD equals:
 0, wire is unattached
 -1, wire is attached at $z=0$
 1, wire is attached at $z=c$
 2, wire is attached at both $z=0$ and $z=c$
- A,B,C -- The dimensions of the cavity in the x, y, z directions, respectively (note that cavity must be oriented such that $A \leq B$)
- XC,YC -- The x-y coordinates of the center of the wire
- R -- The wire radius
- ZL,ZU -- The z coordinates of the wire endpoints, with $ZL < ZU$
- LBDA -- The wavelength (λ) associated with the frequency of operation
- NSM -- Maximum number of terms used for the sum S3

MAX -- Maximum value of m permitted in the sum of
SUBROUTINE BADSUM (See [1], p. 57-58)

MAXX -- Maximum value of m permitted in the sums of
subroutines GM1, GM2, and GM3 (See [1], p. 57-58)

CS,LS -- Convergence criteria for all sums (See [1], p. 57-59)

ADYAD -- Logical variable which controls the method in which
the components of \bar{G}_e are computed. If ADYAD equals:

(.T.) first-order difference techniques are used
to calculate \bar{G}_e from \bar{G}_A using equation (2.2) from [1].

(.F.) components of \bar{G}_e are computed directly

NWALL -- Indicates the cavity wall perforated by the aperture.
If NWALL equals:

1, aperture is in x=0 wall ($\hat{n}=\hat{x}$)
2, aperture is in y=0 wall ($\hat{n}=\hat{y}$)
3, aperture is in z=0 wall ($\hat{n}=\hat{z}$)

XPP,YPP -- The x_1 and x_2 coordinates of the centerpoint of
of the aperture, such that $\hat{a}_1 \times \hat{a}_2 = \hat{n}$ (see [1], p. 23)

RA -- An array containing the semi-axes of the elliptical
aperture in the x_1 and x_2 dimensions, respectively

EMAG,PHASAP,THE,PHI,ANG -- Parameters controlling the incident
plane wave excitation, where

$$\bar{E}^{inc}(\bar{r}) = \hat{a}_e |E_o| e^{-jk \cdot \bar{R}}$$

where \hat{a}_e and \hat{k} are defined in Figure 1 with

$$EMAG = |E_o|, THE = \theta^i, PHI = \phi^i, ANG = \psi^i.$$

If PHASAP = (.F.), phase of incident field is referenced
to the coordinate origin ($\bar{R} = \bar{r}$) and if PHASAP = (.T.),
the phase is referenced to the centerpoint of the
aperture ($\bar{R} = \bar{r} - \bar{r}_a$). Note that all angles are input
in degrees.

FIX -- Logical variable which controls whether or not the
effects of the cavity walls upon the aperture dipole
moments are included (See [1], p. 54). If FIX = (.T.),
such effects are included.

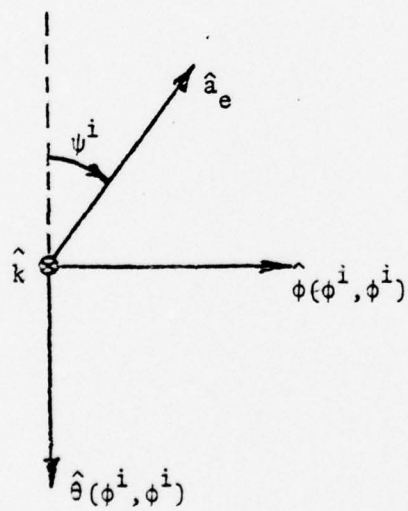
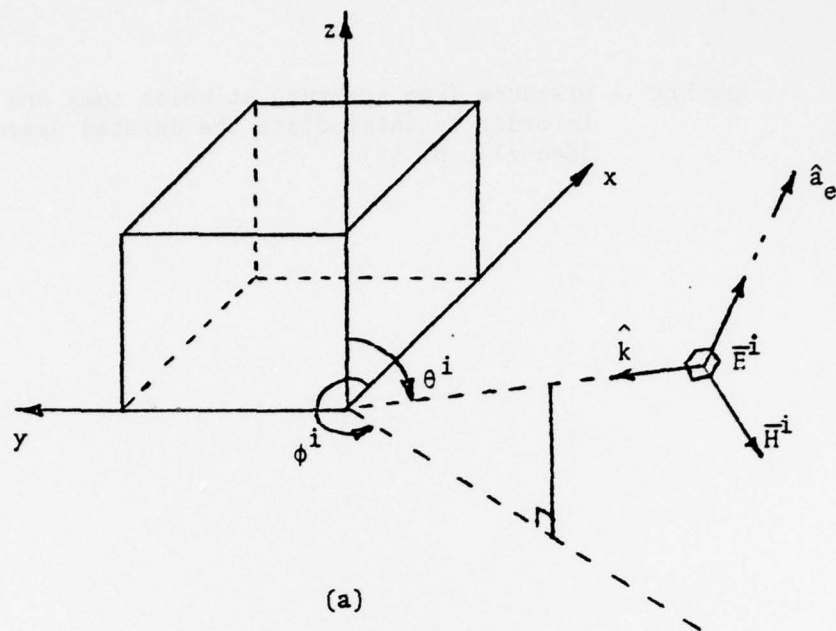


Figure 1. Input Parameters for Incident Plane Wave.

DELFIX -- Distance from aperture at which sums are computed
in order to interpolate the deleted Green's functions
(See [1], p. 68)

CHAPTER 3

OUTPUT

File OUTPUT

The program automatically will create the print file OUTPUT. During normal execution, the input information of the previous chapter will be printed, as well as the aperture polarizabilities α_e , $\alpha_{m_{11}}$ and $\alpha_{m_{22}}$ (see [1], p. 17-19). The solution for the wire current and the total aperture fields (E_{T_n} , H_{T_1} , H_{T_2}) are given. For comparison, the exterior short circuit fields (E_n^{sc-} , H_1^{sc-} , H_2^{sc-}) are also given (see [1], pp. 20-26).

In addition, several messages of an informative or warning nature may be printed during execution. These messages which can be divided into three basic categories, are described below:

Informative messages --

1. NOTE--W(I) INTERPOLATED THRU $I = \underline{n}$

W(I) is an array containing $P(\alpha)$ for $\alpha = (I-1)\Delta$ (see [1], p. 63). For small α , $P(\alpha)$ is interpolated as discussed on p.65 of [1]. This message indicates that this approximation has been made for the first \underline{n} values of $P(\alpha)$. To reduce \underline{n} , increase the size of the input parameter MAX.

Non-Fatal Errors --

1. WARNING -- DIMENSION SIZE EXCEEDED -- name1 TRUNCATED TO n. TO FIX, INCREASE SIZE OF name2 ARRAY(S).

This message indicates that the arrays used for temporary storage in BADSUM, GM1, GM2 and GM3 are not large enough to sum the series to the maximum number of terms specified. The particular input parameter (MAX or MAXX, specified by name1) is truncated and execution is continued. Note that this truncation could subsequently cause either fatal error 5 or 6 listed below. To rectify this problem, increase the size of the array(s) specified by name2, such that $MS1 > \max(\text{MAX}, \text{MAXX})$ and $MS2 > \max(c_1 \text{MAX}, c_2 \text{MAXX})$ where $c_1 = B/A$ and $c_2 = \max(A, B, C) / \min(A, B, C)$.

Fatal Errors --

1. WARNING--MATRIX SIZE EXCEEDS STORAGE ALLOCATION

The input parameter N is too large. Decrease N and/or increase MS such that $MS \geq N + 3$.

2. WARNING--REORIENT CAVITY SUCH THAT A.LE.B

A must be less than or equal to B. Redefine coordinate system such that this is true.

3. WARNING--ERROR IN WIRE END POINTS

Note that $ZL < ZU$ must be true

4. WARNING--ALL OR PART OF THE WIRE IS OUTSIDE THE CAVITY, OR UN-ATTACHED WIRE HAS END POINT ON CAVITY WALL

Check to see that the input parameters do not violate any of the above conditions.

5. NOT ENOUGH POINTS FOR INTERPOLATION

Interpolation of $P(\alpha)$ requires its numerical evaluation at at least two points. This is not possible with the present input value of MAX. To correct this problem, increase MAX.

6. WARNING--GMI SUM NOT CONVERGED c l

The value of MAXX is not sufficient to obtain the specified convergence (CS,LS) in GM1, GM2, or GM3. Note that c is the convergence ratio at the last term and l is the number of consecutive times, if any, the specified convergence ratio CS has been met. To rectify this problem, increase MAXX and/or reduce the severity of the convergence specified by CS and LS.

7. WARNING--SUM 3 NOT CONVERGED c l

The value of NSM is not sufficient to obtain the specified convergence (CS,LS) in S3. Note that c and l are defined as in 6 above. To rectify, increase NSM and/or reduce the severity of the convergence specified by CS and LS.

8. WARNING--CAVITY DIMENSION TOO SMALL FOR DPLFIX

This error is caused by insufficient room inside the cavity to perform the interpolation necessary for the evaluation of the deleted Green's functions in SUBROUTINE DPLFIX. To correct, either decrease the size of DELFIX or let $FIX = (.F.)$.

File PUNCH

The program will in certain situations create the punch file PUNCH. This file contains the information from the file INPUT, as

well as the solution for the wire current and the fields ($E_{T_n}, H_{T_1}, H_{T_2}$). The file is formatted according to the PUNCH statements found at the end of PROGRAM START. The PUNCH file will be created only if execution has not been abnormally halted and if sense switch 1 is "on". This can be accomplished on CDC machines with the SCOPE control card ONSW(1).

CHAPTER 4

DESCRIPTION OF PROGRAM AND SUBPROGRAMS

The programs and subprograms listed in this chapter are those used in the code described in this document. Uniformly throughout the following description, it is to be understood that variables (X, Y, Z) represent \bar{r} or (x,y,z) and that (XP,YP,ZP) represent \bar{r}' or (x',y',z'). Similarly, other program variables (denoted in capital letters) obviously represent physical variables of the problem (for example, A, B and C represent the cavity dimensions a, b, and c). Only when such a connection is not obvious will it be explicitly noted. A complete program listing is given in the appendix.

PROGRAM START

This program's role is primarily that of input/output operations. In addition, it also provides for the checking of consistency among the various input parameters. Finally, it directs program execution by calling the basic matrix filling and inverting subprograms. It is important to note that if the size of the arrays in blank COMMON are changed, the appropriate values of MS, MS1, and MS2 should be changed accordingly to insure proper error checking. Sufficient dimension size can be obtained by adhering to the algorithms listed in chapter 3 under non-fatal error 1 and fatal error 1.

SUBROUTINE FILL

This subroutine fills the matrix \overline{Q}^a (see [1], p.52,63) for the case of an unattached wire. The necessary values of $P(\beta)$ are provided by a call to SUBROUTINE GETUM.

SUBROUTINES FILL1 and FILL2

These subroutines fill the matrix \overline{Q}^a for the cases of the wire attached to the cavity walls at one or both ends respectively. They incorporate the necessary modifications to account for non-zero half-pulse and the half-testing functions which are needed at the attached ends of the wire (see [1], p.50). As in SUBROUTINE FILL, the necessary values of $P(\beta)$ ([1], p.63) are provided by calling SUBROUTINE GETUM.

SUBROUTINE GETUM

This subroutine fills the array $W(I)$ with the necessary values of $P(\beta)$ to fill the matrix. It will automatically interpolate $P(\beta)$ for sufficiently small β (see [1], p.65) using a three-point fit to a second order polynomial in β .

SUBROUTINE MORFIL

This subroutine fills the matrices \overline{Q}^b and \overline{Q}^c according to (4.7) and (4.8) in [1]. In addition it also initializes \overline{Q}^d to \overline{I} , the identity dyad. The necessary components of the dyads have been calculated in SUBROUTINE EAP (through calls to SUBROUTINES EDIPL and MDIPL) and are contained in the arrays FP , $G1$ and $G2$. Note that advantage is taken of the fact that $\overline{G}_e(\overline{r}, \overline{r}') = \overline{G}_e(\overline{r}', \overline{r})$ and $\overline{g}_e(\overline{r}, \overline{r}') = -\overline{G}_H(\overline{r}', \overline{r})$ (see [1], Table 2 and (2.7)).

SUBROUTINE INVERS

This subroutine numerically solves the resulting matrix equation (4.5) in [1] using partial-pivoting Gauss Elimination.

SUBROUTINE FIXUP

This subroutine fills the matrix \bar{Q}^d according to (4.9) in [1]. This routine is called only if the input parameter FIX = (.T.). The values of the deleted Green's functions, which are calculated by SUBROUTINE DPLFIX, are supplied to this subprogram through the common block/WHYNOT/.

SUBROUTINE DPLFIX

This subroutine calculates the deleted Green's functions as outlined on pp. 67-70 of [1]. It is called by START only if FIX = (.T.). Figures 2 (a and b) show arrangement of points at which the components of \bar{G}_A and \bar{g}_F are calculated, respectively. Note that Δ in Figure 2 represents the input parameter DELFIX. These computations are somewhat complicated by the fact that if the aperture is sufficiently close to one or more of the side walls of the cavity the choice of points in Figure 2 must be modified such that all points remain on the cavity interior surface. In addition, when the aperture is close to a side wall, it is necessary to remove the image source in that wall before interpolation, and then to subsequently add it to the interpolated result. Because of these two complications, extensive logic is necessary in DPLFIX to adequately handle them.

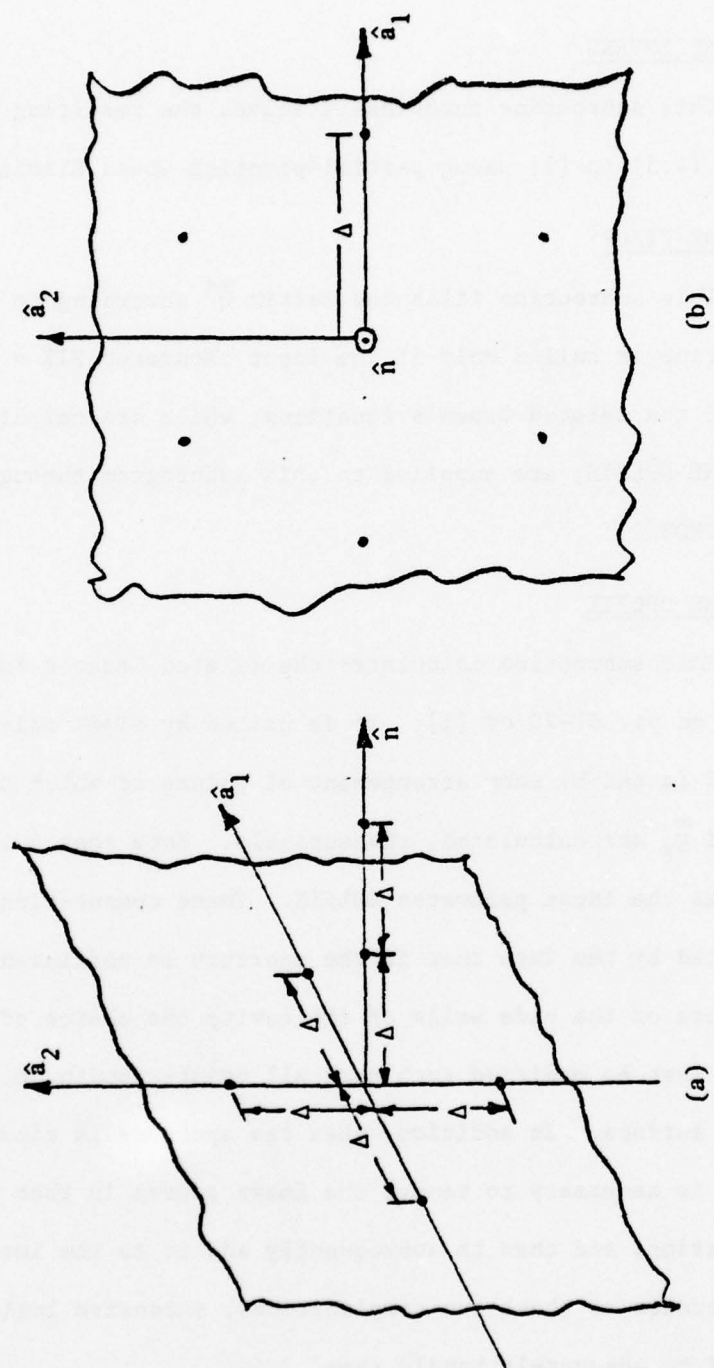


Figure 2. Points Used for Interpolation of (a) $\hat{G}_{A_{nn}}$, and (b) $\hat{g}_{F_{11}}$.

SUBROUTINE EAP

This subroutine calculates several quantities relating to the aperture. It calls subroutines to compute the aperture polarizabilities, and the components of \bar{G}_h and \bar{g}_e necessary to fill \bar{Q}^b and \bar{Q}^c . In addition it calls routines which convert the exterior incident field from the input parameters (shown in Figure 1) to the x,y,z components of E and H. These values are then used to fill the excitation vector in (4.5) of [1] into the array E(I).

SUBROUTINE INC

This subroutine converts the input specifications for the incident field (EMAG,ANG,THE,PHI) to the corresponding components of E and H in the spherical polar coordinate system.

SUBROUTINE CONV

This subroutine converts a vector from its polar components to its cartesian components. It is assumed that the vector is perpendicular to the polar unit vector \hat{r} .

SUBROUTINE ALPHA

This subroutine computes the aperture polarizabilities for the elliptic aperture using (2.15) of [1]. It calls SUBROUTINE ELLIPTIC to provide the necessary values of the elliptic integrals.

SUBROUTINE ELLIPTIC

This subroutine computes the complete elliptic integrals of the first and second kinds of argument X which are denoted EK and E, respectively. They are computed using the polynomial approximations of [2], pp. 591-592.

SUBROUTINE MDIPL

This subroutine calculates $G_{h_{Jz}}(\bar{r}_a, \bar{r}_p)$ for use in the matrix \bar{Q}^c . It fills the array E with these values for $p = 1, N$.

SUBROUTINE EDIPL

This subroutine calculates $G_{e_{Jz}}(\bar{r}_a, \bar{r}_p)$ for use in matrix \bar{Q}^c . It fills the array E with these values for $p = 1, N$. Note that if $ADYAD = (.T.)$, these values are computed indirectly by first computing appropriate values of $G_{A_{zz}}$ and using first-order finite difference techniques.

FUNCTION S3

This function numerically computes the function S_3 , defined by (3.2c) in [1], using (3.16) in [1].

SUBROUTINES GA, GF, GM and GE

These subroutines compute the various components of the dyadic Green's functions needed in the matrices \bar{Q}^b , \bar{Q}^c and \bar{Q}^d (see [1], pp.52-54). Note that these subroutines automatically analytically reduce the sum that will result in the most rapidly converging remaining double sum (see [1], p. 55). Note that IN, SX and SY are dummy arrays and the answer is returned as SD. Table 1 shows the way to call these subroutines to compute any desired dyad component.

SUBROUTINE BADSUM

This subroutine computes the indefinite integral of the reduced kernel $P(\beta)$ defined by (4.22) in [1]. The m-n plane is subdivided into

Table 1. Appropriate subroutine call and value of GEZ to compute the various dyad components.

<u>To Compute</u>	<u>CALL</u>	<u>GEZ</u>
$G_{A_{xx}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, Y, YP, Z, ZP, X, XP, B, C, A, SD)	F
$G_{A_{yy}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, Z, ZP, X, XP, Y, YP, C, A, B, SD)	F
$G_{A_{zz}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, X, XP, Y, YP, Z, ZP, A, B, C, SD)	F
$g_{F_{xx}}(\bar{r}, \bar{r}')$	GF(IN, SX, SY, X, XP, Y, YP, Z, ZP, A, B, C, SD)	F
$g_{F_{yy}}(\bar{r}, \bar{r}')$	GF(IN, SX, SY, Y, YP, Z, ZP, X, XP, B, C, A, SD)	F
$g_{F_{zz}}(\bar{r}, \bar{r}')$	GF(IN, SX, SY, Z, ZP, X, XP, Y, YP, C, A, B, SD)	F
$G_{e_{xx}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, Y, YP, Z, ZP, X, XP, B, C, A, SD)	T
$G_{e_{xy}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, XP, X, ZP, Z, YP, Y, A, C, B, SD)	F
$G_{e_{xz}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, XP, X, YP, Y, ZP, Z, A, B, C, SD)	F
$G_{e_{yx}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, X, XP, Z, ZP, Y, YP, A, C, B, SD)	F
$G_{e_{yy}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, Z, ZP, X, XP, Y, YP, C, A, B, SD)	T
$G_{e_{yz}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, YP, Y, XP, X, ZP, Z, B, A, C, SD)	F
$G_{e_{zx}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, X, XP, Y, YP, Z, ZP, A, B, C, SD)	F
$G_{e_{zy}}(\bar{r}, \bar{r}')$	GE(IN, SX, SY, Y, YP, X, XP, Z, ZP, B, A, C, SD)	F
$G_{e_{zz}}(\bar{r}, \bar{r}')$	GA(IN, SX, SY, X, XP, Y, YP, Z, ZP, A, B, C, SD)	T
$-G_{h_{xy}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, XP, X, ZP, Z, YP, Y, A, C, B, SD)	F
$G_{h_{xz}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, XP, X, YP, Y, ZP, Z, A, B, C, SD)	F
$G_{h_{yx}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, YP, Y, ZP, Z, XP, X, B, C, A, SD)	F
$-G_{h_{yz}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, YP, Y, XP, X, ZP, Z, B, A, C, SD)	F
$-G_{h_{zx}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, ZP, Z, YP, Y, XP, X, C, B, A, SD)	F
$G_{h_{zy}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, ZP, Z, XP, X, YP, Y, C, A, B, SD)	F

Table 1.--Continued

<u>To Compute</u>	<u>CALL</u>	<u>GEZ</u>
$-g_{e_{xy}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, Y, YP, Z, ZP, X, XP, B, C, A, SD)	F
$g_{e_{xz}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, Z, ZP, Y, YP, X, XP, C, A, B, SD)	F
$g_{e_{yx}}(\bar{r}, \bar{r}')$	GM, IN, SX, SY, X, XP, Z, ZP, Y, YP, A, C, B, SD)	F
$-g_{e_{yz}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, Z, ZP, X, XP, Y, YP, C, A, B, SD)	F
$-g_{e_{zx}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, X, XP, Y, YP, Z, ZP, A, B, C, SD)	F
$g_{e_{zy}}(\bar{r}, \bar{r}')$	GM(IN, SX, SY, Y, YP, X, XP, Z, ZP, B, A, C, SD)	F

elliptical bands as discussed on pp. 55-59 of [1] and the double sum is evaluated using the convergence criteria discussed on those pages. If the sum does not converge in the allotted number of terms, the logical variable CIND is set to (.T.) and control is returned to the calling subprogram. SX and SY are input arrays defined as

$$SX(I) = \text{sink}_x x \text{ sink}_x x', \quad k_x = \frac{\pi}{a} I$$

and

$$SY(I) = \text{sink}_y y \text{ sink}_y y', \quad k_y = \frac{\pi}{b} I$$

The input X represents β and $P(\beta)$ is returned as SD.

SUBROUTINES GM1, GM2 and GM3

These subroutines numerically sum two dimensional series of the following form:

$$GM1 = \frac{1}{ab} \sum_{\substack{m=m_0 \\ n=n_0}}^{\infty} \frac{\varepsilon_m \varepsilon_n u v w}{\gamma_c \sinh \gamma_c c}$$

where

$$w_{mn} = \begin{cases} \sinh \gamma_c z < \sinh \gamma_c (c-z), & I=1 \\ \gamma_c \sinh \gamma_c z \cosh \gamma_c z', & I=2 \\ \Gamma_1 \cosh \gamma_c z < \cosh \gamma_c (c-z), & I=3 \end{cases}$$

and

$$\Gamma_1 = \begin{cases} 1, & \text{GEZ} = (.F.) \\ k_c^2, & \text{GEZ} = (.T.) \end{cases}$$

for $k_x = \frac{m\pi}{a}$, $k_y = \frac{n\pi}{b}$, $k_c^2 = k_x^2 + k_y^2$ and $\gamma_c^2 = k_c^2 - k^2$. Note that the input arrays SX and SY are defined as

$$SX(I) = u_{(I-1+m_0)} \text{ and } SY(I) = v_{(I-1+n_0)}$$

and m_0 and n_0 can each be either 0 or 1. This sum is performed in the same fashion as SUBROUTINE BADSUM and the same convergence criteria is used. Note that if convergence is not achieved, execution is halted and a warning message is printed.

SUBROUTINES NSS, NCC and NSC

These subroutines fill the array D in the following ways:

$$D(I) = \begin{cases} \sin k_x x \sin k_x x', & (\text{NSS}) \\ \Gamma_2 \cos k_y y \cos k_y y', & (\text{NCC}) \\ k_z \sin k_z z \cos k_z z', & (\text{NSC}) \end{cases}$$

where

$$\Gamma_2 = \begin{cases} 1, & \text{GEZ} = (.F.) \\ k^2 - k_y^2, & \text{GEZ} = (.T.) \end{cases}$$

$k_x = \frac{\pi}{a} I$, $k_y = \frac{\pi}{b} (I-1)$ and $k_z = \frac{\pi}{c} I$. This subroutine is used to appropriately fill the SX and SY arrays for use in BADSUM, GM1, GM2 or GM3.

SUBROUTINE NDE

This subroutine is a dummy routine to call either NSS, NCC or NSC, depending upon the value of the integer L.

FUNCTIONS COSH and SINH

These functions compute the hyperbolic cosine and sine, respectively, of argument X.

FUNCTIONS RSS, RCC, RCS and RSINH

These functions compute the ratios of various combinations of hyperbolic functions. They are defined by

$$\text{RSS}(X,Y,Z) = \frac{\sinh X \sinh Y}{\sinh Z}$$

$$\text{RCC}(X,Y,Z) = \frac{\cosh X \cosh Y}{\sinh Z}$$

$$\text{RCS}(X,Y,Z) = \frac{\cosh X \sinh Y}{\sinh Z}$$

and

$$\text{RSINH}(X,Y) = \frac{\sinh X}{\sinh Y}$$

REFERENCES

1. Seidel, D. B., "Excitation of a Wire in a Rectangular Cavity, Part I: Theory," Air Force Office of Scientific Research, Grant No. AFOSR76-3009, Final Report, Engineering Experiment Station, University of Arizona, Tucson, Arizona, June 1977.
2. Abramowitz, M. and I. Stegun, Handbook of Mathematical Functions, New York: Dover, 1965.

APPENDIX

LISTING OF COMPUTER PROGRAMS

```

PROGRAM START(INPUT,OUTPUT,PUNCH)
LOGICAL GEZ,ADYAD,FIX,PHASAP
COMPLEX Q,D,S,ESC(3)
REAL K,KK,LBDA
DIMENSION RA(2)
COMMON/LAST2/RA,EMAG,ANG,THE,PHI,PHASAP
COMMON/SPEC/GEZ
COMMON/TYPE/ADYAD
COMMON/WN/K
COMMON/FSUM/A,B,C,MAX
COMMON/GM/MAXX
COMMON/GRD/IGRD
COMMON/SUMS/KK,NSM,CS,LS
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
COMMON/LAST/XPP,YPP,NWALL
C*****WARNING--DO NOT CHANGE DIMENSIONING OF ARRAYS IN BLANK COMMON
C*****WITHOUT CHANGING APPROPRIATE VALUES OF MS,HSI AND/OR MS2!!!
1  COMMON Q(36,36),SX(86),SY(285)
DATA HS,MS1,MS2/36,86,285/
C*****EIA/376.7/*****
DATA GEZ/.F./
DATA PI/3.1415927/
DATA XAM,XXAM/4H-MAX,4HMAXX/
CALL SWITCH(1,IPUNCH)
READ 100,N,IGRD
READ 101,A,B,C,XC,YC,K,ZL,ZU
READ 102,NSM,MAX,MAXX,LS,CS,ADYAD
READ 800,PHASAP,NWALL,XPP,YPP,RA,EMAG,ANG,THE,PHI
READ 202,FIX,DEL,FI
N3=N+3
PRINT 99
PRINT 300
IF(IGRD)19,20,21
PRINT 129
ZL=0.23
GOTO 23
7U=C
IF(IGRD.EQ.1)GOTO 31
PRINT 132
GOTO 30
PRINT 131
GOTO 23
PRINT 130
IF(ZL.EQ.0.0..OR.ZU.EQ.C)GOTO 22

```

19
30
21
31
20


```

23      PRINT 301,A,R,C, LBDA
        PRINT 302,R,ZL,ZU,XC,YC
        PRINT 303,NSM,MAX,MAXX,CS,LS,ADYAD
        IF(ZL-LT.O.OR,ZU-GT.C)GOTO 22
        IF(ZU-GT.ZL)GOTO 17
        PRINT 116
        STOP
        IF(XC-LT.A.A.XC.GT.O..A.YC.LT.B.A.YC.GT.O.)GOTO 18
        PRINT 117
        STOP
        IF(A-LE.B)GOTO 11
        PRINT 110
        STOP
        IF(MS-GE.N3)GOTO 12
        PRINT 111
        STOP
        IF(MS1-GI.MAX)GOTO 13
        MAX=MS1-1
        PRINT 112, XAM,MAX
        CON=B/A
        NAX=CON*MAX
        IF(MS2-GI.NAX)GOTO 14
        MAX=(MS2-1)/CON
        PRINT 113,XAM,MAX
        IF(MS1-GI.MAXX)GOTO 15
        MAXX=MS1-1
        PRINT 112,XXAM,MAXX
        CON=AMAX1(A,B,C)/AMIN1(A,B,C)
        NAX=CON*MAXX
        IF(MS2-GI.NAX)GOTO 16
        MAXX=(MS2-1)/CON
        PRINT 113,XXAM,MAXX
        NAX=B/A*MAX
        KK=2.*PI/LBDA
        KK=K*KK
        DEL=(ZU-ZL)/(N+1-IABS(IGRD))
        HDEL=.5*DEL
        CKD=2.*CKD*(K*DEL)
        CON=2.-CKD
        DQ=-.5*S3(YC,XC,XC+R,B,A)
        CALL NSS(SX,XC,XC+R,A,MAX)
        CALL NSS(SY,YC,YC+R,B,MAX)
        IF(IGRD)1,2,3
        IF(IGRD.EQ.1)GOTO 1
        CALL FILL2(IN,SX,SY,S,Q,MS,DQ)
        GOTO 4
3

```



```

1 2 3
300 *EXTERIOR*/25X*REAL*14X*IMAGINARY*18X*KEAL*14X*IMAGINARY*
301 //10X*EN:2E20.5,5X,2E20.5/10X*H1:2E20.5,5X,2E20.5/10X
302 *H2:2E20.5,5X,2E20.5)
303 *FORMAT(20X*APERTURE-EXCITED WIRE IN A RECTANGULAR CAVITY*//)
304 *C=*E10.3,5X*80X*DIMENSIONS: A=*E10.3,5X*B=*E10.3,5X
*ZL=*E10.3,5X*WIRE SIZE AND LOCATION:*/10X*RADIUS=*E10.3,5X
*ZL=*E10.3,5X*ZU=*E10.3,5X*XC=*E10.3,5X*YC=*E10.3,5X
*FORMAT(5X*NUMBER OF PULSES USED IN CURRENT EXPANSION: N=*I3/)
*SUM 3: NSM=*I4/10X*CONVERGENCE CRITERION, ETC.*/10X*MAXIMUM TERM FOR *
*MAX=*I4/10X*MAXIMUM TERM FOR GMY SUM: *
*MAXX=*I4/10X*CONVERGENCE RATIO: CS=*E10.3/10X
*REPEATED IN CALCULATING INCIDENT FIELD (I/F): ADYAD=*I1/)
*FORMAT(10X*NOTE--DIPOLE APPROXIMATIONS ACCOUNT FOR WALL RE*
*FLECTIONS (FIX=.T.) WITH DELFIX=*E10.3/)
*FORMAT(L1,I1,8E9.2)
1 2 3
305 STOP
800 END

```

```

SUBROUTINE FILL(IN,SX,SY,D,S,Q,MS,DO,W)
1 DIMENSION IN(1),SX(1),SY(1),D(1),S(1),Q(MS,1),
W(1),
2 COMPLEX Q,CE
REAL K
COMMON/WN/K
COMMON/FSUM/A,B,C,MAX
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
DATA CE/(0.,-376.7)/
NP=N+1
NNP=NP+NP
X=2.*ZL+HDEL
CALL GETUM(D,DQ,X,NNP,IN,SX,SY)
DO 2 I=2,NNP
J=I-1
S(J)=D(I)-D(J)
X=HDEL
CALL GETUM(W,DQ,X,NNP,IN,SX,SY)
D(1)=2.*W(1)
DO 1 I=2,NNP
D(I)=W(I)-W(I-1)
DZ=2.*D(2)-CKD*D(1)
DO 3 I=1,N
IP=I+1

```

```

IJ=I+1
Q(I,I)=(DZ+S(IJ-1)+S(IJ+1)-CKD*S(IJ))*CE
IF(I.EQ.N)GOTO3
DO 4 J=IP,N
IJ=I+J
JI=J-I
Q(J,I)=(D(JI)+D(JI+2)+S(IJ-1)+S(IJ+1)
-CKD*(D(JI+1)+S(IJ)))*CE
Q(I,J)=Q(J,I)
CONTINUE
RETURN
END

```

1

4 3

```

SUBROUTINE FILL1(IN,SX,SY,S,Q,MS,DQ)
DIMENSION IN(1),SX(1),SY(1),S(1),Q(MS,1)
COMPLEX Q,CE
REAL K
COMMON/WN/K
COMMON/FSUM/A,B,C,MAX
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
LOGICAL HI
COMMON/GRD/IGRD
DATA CE/10.,-376.7)/
HI=IGRD.EQ.1
NN=N+N
X=HDEL
NNP=NN+2
NP=N+1
CALL GETUM(S,DQ,X,NN,IN,SX,SY)
DO 1 I=2,NN
J=NNP-I
S(J)=S(J)-S(J-1)
S(1)=2.*S(1)
M=1
IF(HI)M=N
DZ=2.*S(2)-CKD*S(1)
Q(M,M)=CE*DZ
DO 6 J=2,N
JJ=J
IF(HI)JJ=NP-J
Q(JJ,M)=(S(J-1)+S(J+1)-CKD*S(J))*CE
Q(M,JJ)=Q(JJ,M)*2.
DO 2 I=2,N
II=I
IF(HI)II=NP-I

```

1

6


```

DO 2 J=I,N
JJ=J
IF(HI)JJ=NP-J
JI=Y+J
IF(I.EQ.J)GOTO10
IJ=J-I
Q(I,I,JJ)=(S(IJ+2)+S(JI-2)+S(IJ)+S(JI)-CKD*(S(IJ+1)+S(JI-1)))*CE
Q(JJ,II)=Q(II,JJ)
CONTINUE
RETURN
Q(II,II)=(DZ+S(JI-2)+S(JI)-CKD*S(JI-1))*CE
GOTO 3
END

```

3
2
10

```

SUBROUTINE FILL2(IN,SX,SY,S,Q,MS,DQ)
DIMENSION IN(1),SX(1),SY(1),S(1),Q(MS,1)
COMPLEX Q,CE
REAL K
COMMON/WN/K
COMMON/FSUM/A,B,C,MAX
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
LOGICAL HI
COMMON/GRD/IGRD
DATA CE/(0.,-376.7)/
NP=N+1
NNP=NP+2
X=HDEL
NM=N-1
CALL GETUM(S,DQ,X,NP,IN,SX,SY)
DO 1 I=2,NP
J=NNP-I
S(J)=S(J)-S(J-1)
S(1)=2.*S(1)
DZ=2.*S(2)-CKD*S(1)
Q(1,1)=CE*DZ
Q(N,N)=Q(1,1)
Q(1,N)=CE*(2.*S(NM)-CKD*S(N))
Q(N,1)=Q(1,N)
DO 6 J=2,NH
JJ=VP-J
Q(J,1)=(S(J-1)+S(J+1)-CKD*S(J))*CE
Q(JJ,N)=Q(J,1)
Q(1,J)=2.*Q(J,1)
Q(N,JJ)=Q(1,J)

```

1

6

```

DO 2 I=2,N
II=NP-I
IF(I.GT.II) GOTO 4
DO 2 J=I,II
JJ=NP-J
JI=I+J
IF(I.EQ.J)GOTO 10
IJ=J-I
Q(I,J)=(S(IJ+2)+S(JI-2)+S(IJ)+S(JI)-CKD*(S(IJ+1)+S(JI-1)))*CE
Q(I,I,J)=Q(I,J)
Q(J,I,I)=Q(I,J)
Q(J,J,II)=Q(I,J)
CONTINUE
CONTINUE
CONTINUE
RETURN
Q(I,I)=(DZ+S(JI-2)+S(JI)-CKD*S(JI-1))*CE
Q(II,II)=Q(I,I)
GOTO 3
END

```

3
2
4
10

```

SUBROUTINE GETUM(W,DQ,ST,NP,IN,SX,SY)
COMMON/FFR/FILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
LOGICAL CIND
COMMON/YES/CIND
DIMENSION W(1),IN(1),SX(1),SY(1)
DATA PI/3.1415927/
X=NP*DEL+ST
NP2=NP+1
CIND=.F.
DO 1 I=1,NP
J=NP2-I
X=X-DEL
CALL BADSUM(IN,SX,SY,X,SD)
IF(CIND)GOTO 10
W(J)=SD-DQ
RETURN
PRINT 11,J
FORMAT(10X*NOTE--W(I) INTERPOLATED THRU I=*I2/)
NS=J+1
X=X+DEL
J1=NS+1
X1=X+DEL
IF(J1.GT.NP)GOTO21
CD=.25/PI

```

1
10
11

```

XN=X/R
CC1=W(IN$)-CO*ALOG(XN+SQRT(XN*XN+1.))
XN=X1/R
CC2=W(J1)-CO*ALOG(XN+SQRT(XN*XN+1.))
B=(CC2-X1*CC1/X)/X1/DEL
A=(CC1-B*X*X)/X
X=ST-DEL
DO 6 I=1,J
  X=X+DEL
XN=X/R
W(I)=CO*ALOG(XN+SQRT(XN*XN+1.))+X*(A+B*X)
RETURN 31
STOP
FORMAT(10X*NOT ENOUGH POINTS FOR INTERPOLATION.*)
END

```

6
21
31

```

SUBROUTINE MORFIL(Q,MS,FP,G1,G2,CON)
DIMENSION Q(MS,1),FP(1),G1(1),G2(1),ALPM(2)
COMPLEX Q,CC,CE
COMMON/DIPOLE/XP,YP,ZP,ALPE,ALPM,NWALL
COMMON/GRD/IGRD
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
COMMON/NEXTRA/N1,N2,N3
DATA CE/(0.,-376.7)/
CC=CE*CON
DO 1 I=1,N
  Q(I,N1)=CON*ALPE*FP(I)
  Q(I,N2)=-CC*ALPM(1)*G1(I)
  Q(I,N3)=-CC*ALPM(2)*G2(I)
  Q(N1,I)=CE*DEL*FP(I)
  Q(N2,I)=DEL*G1(I)
  Q(N3,I)=DEL*G2(I)
DO 2 I=N1,N3
  DO 3 J=N1,N3
    Q(I,J)=(0.,0.)
  Q(I,I)=(1.,0.)
  IF(IGRD.EQ.0.0.IGRD.EQ.1)GOTO 5
DO 4 I=N1,N3
  Q(I,1)=Q(I,1)*.5
  IF(IGRD.LT.1)RETURN
DO 6 I=N1,N3
  Q(I,N)=Q(I,N)*.5
RETURN
END

```

1
3
2
4
5
6

```

C SUBROUTINE INVERS (AM,M1,M2,NPTS,C,B)
SUBROUTINE INVERS INVERTS THE EQUATION AM(I,J) B(J) = C(I) AND RETURN
COMPLEX AM,B,C,TEMP,SUM,BETA
DIMENSION AM(M1,M2),C(M1),B(M2)
IF (NPTS.GT. M1 .OR. NPTS.GT. M2) GO TO 1
NM1 = NPTS - 1
DO 690 KK = 1,NM1
KKP1 = KK + 1
L = KK
DO 600 I = KKP1,NPTS
D=REAL(AM(I,KK))
P=AIMAG(AM(I,KK))
S=REAL(AM(L,KK))
T=AIMAG(AM(L,KK))
IF ( (D*D+P*P).GT. (S*S+T*T) ) L = I
DO 610 J = KK,NPTS
TEMP=AM(KK,J)
AM(KK,J)=AM(L,J)
AM(L,J)=TEMP
TEMP=C(KK)
C(KK)=C(L)
C(L)=TEMP
DO 690 I = KKP1,NPTS
BETA = AM(I,KK) / AM(KK,KK)
DO 650 J = KKP1,NPTS
AM(I,J) = AM(I,J) - BETA*AM(KK,J)
C(I) = C(I) - BETA*C(KK)
B(NPTS) = C(NPTS) / AM(NPTS,NPTS)
I = NM1
IP1 = I + 1
SUM = (0.0,0.0)
DO 700 J = IP1,NPTS
SUM = SUM + AM(I,J)*B(J)
B(I) = ( C(I) - SUM ) / AM(I,I)
I = I - 1
IF (I.GE.1 ) GO TO 710
RETURN
PRINT 10
FORMAT (//*) WARNING - MATRIX SIZE EXCEEDS STORAGE ALLOCATION*
10 1
END

```



```

SUBROUTINE FIXUP(Q,MS)
REAL K
COMPLEX Q, CHGA, CHGF(2), CE, CK, COK
DIMENSION Q(MS,1), DGX(2), DGYX(2), ALPM(2)
COMMON/WHYNOT/CHGA, CHGF, DGAX, DGAY, DGX, DGYX
COMMON/WN/K
COMMON/FORFILL/N, DEL, HDEL, ZL, XC, YC, R, CKD
COMMON/DIPOLE/XP, YP, ZP, ALPE, ALPM, NWALL
COMMON/NEXTRA/N1, N2, N3
DATA CE/(0., -376.7)/
CK=CE*K
COK=K/CE
Q(N1,N1)=1.+ALPE*CHGA
Q(N1,N2)=CK*ALPM(1)*DGX(1)
Q(N1,N3)=-CK*ALPM(2)*DGX(2)
Q(N2,N1)=-COK*ALPE*DGAY
Q(N3,N1)=-COK*ALPE*DGAX
Q(N2,N2)=1.-ALPM(1)*CHGF(1)
Q(N3,N3)=1.-ALPM(2)*CHGF(2)
Q(N2,N3)=-ALPM(2)*DGYX(2)
Q(N3,N2)=-ALPM(1)*DGYX(1)
RETURN
END

```

```

SUBROUTINE DPLFIX(DEL, IN, SX, SY, XPF, YPP, NWALL)
COMPLEX CQ, CHGA, CHGF(2)
REAL K, KK
DIMENSION QX(6), QY(6), QA(6), QB(6), IN(1), SX(1), SY(1), XA(1)
, DGX(2), DGYX(2)
COMMON/WN/K
COMMON/FSUM/A, B, C, MAX
COMMON/SUMS/KK, NSM, CONV, LC
COMMON/WHYNOT/CHGA, CHGF, DGAX, DGAY, DGX, DGYX
DATA PI/3.1415927/
CH=5/PI
CN=CM/DEL
CQ=CHPLX(0., K/PI/3.)
XKD=K*DEL
CD=CN*COS(XKD)
CDD=.5*CN*COS(2.*XKD)
ZP=0.
XP=XPP
YP=YPP
IF(NWALL-2)1,2,3
CC=4

```

1

2	AA=B GOTO 4 CC=B AA=C RR=A GOTO 4 CC=C AA=A BB=B Z=ZP+DEL IXL=0 IXU=0 IYL=0 IYU=0 IF(XP+DEL.GE.AA)IXU=1 IF(YP+DEL.GE.BB)IYU=1 IF(YP-DEL.LE.0.)IYL=1 IF(XP-DEL.LE.0.)IXL=1 IX=IXU+IYL IY=IYU+IYL IF(IX.EQ.2.D.IY.EQ.2)GOTO 77 ISUM=IX+IY IF(ISUM.EQ.0)GOTO 29 IF(IXU.EQ.0)GOTO 21 XS=AA+XP YS=YP IF(IXL.EQ.0)GOTO 22 XS=-XP YS=YP IF(ISUM.EQ.2)GOTO 24 IF(IYU.EQ.0)GOTO 23 YS=BB+YP XS=XP IF(IYL.EQ.0)GOTO 29 YS=-YP XS=XP GOTO 29 IF(IYU.EQ.0)GOTO 25 YSI=YP+BB GOTO 29 YSI=-YP CONTINUE CALL GA(IN, SX, SY, XP, YP, Z, ZP, AA, BB, CC, SA) SA=SA-CD ZI=Z+DEL CALL GA(IN, SX, SY, XP, YP, YP, ZI, ZP, AA, BB, CC, SB)
21	
22	
23	
24	
25	
29	

26	SB=SB-CDD IF(I SUM.EQ.0)GOTO 26 ISE=-1 X=XP Y=YP XI=X YI=Y GOTO 70 DGNN=2.* (SB-SA)/DEL/DEL/3. GAA=(4.*SA-SB)/9. D1=DEL X=XP+DEL IF(X.LT.AA)GOTO 5 D1=AA-XP X=AA SA=0. GOTO 6 CALL GA(IN,SX,SY,X,XP,YP,YP,ZP,AA,BB,CC,SA) SA=SA-CM*COS(K*D1)/D1 D2=DEL XI=XP-DEL IF(XI.GT.0.)GOTO 7 D2=XP XI=0. SB=0. GOTO 8 CALL GA(IN,SX,SY,XI,XP,YP,YP,ZP,AA,BB,CC,SB) SB=SB-CM*COS(K*D2)/D2 IF(I SUM.EQ.0)GOTO 27 ISE=0 Z=ZP ZI=Z GOTO 70 DGAX=(SA-SB)/(D1+D2) GAA=GAA+(SA+SB)/6. D1=DEL Y=YP+DEL IF(Y.LT.BB)GOTO 9 Y=BB D1=BB-YP SA=0. GOTO 10 CALL GA(IN,SX,SY,XP,XP,YP,ZP,AA,BB,CC,SA) SA=SA-CM*COS(K*D1)/D1 D2=DEL YI=YP-DEL IF(YI.GT.0.)GOTO 11
5	
6	
7	
8	
27	
9	
10	
.	

```

11      D2=YP
12      Y1=0.
      GOTD 12
      CALL GA(IN, SX, SY, XP, Y1, YP, ZP, ZP, AA, BB, CC, SB)
      SB=SB-CM*COS(K*D2)/D2
      IF(IISUM.EQ.0)GOTO 28
      ISE=1
      X=XP
      X1=X
      GOTD 70
      OGAY=(SA-SB)/(D1+D2)
      GAA=GAA+(SA+SB)/6.
      IF(IISUM.NE.0)GOTO 72
      CHGA=DCNN+KK*(GAA+C0)
      DD 49 IQD=1,2
      CD=.5
      SD=.86602540378444
      SS=C0
      CS=SD
      DD 13 I=1,3
      DY=CS*DEL
      DX=SS*DEL
      DY=DY+DY
      Y=YP+DY
      IF(Y.GT.BB)GOTO 14
      IF(Y.LT.0.)GOTO 15
      X=XP+DX
      DA=DX
      IF(X.LT.AA)GOTO 17
      DA=AA-XP
      SA=0.
      GOTD 18
      CALL GF(IN, SX, SY, X, XP, Y, YP, ZP, ZP, AA, BB, CC, SA)
      DAA=DAA+DA
      D1=SQRT(DAA+DYY)
      SA=SA-CM*COS(K*D1)/D1
      QX(I)=DA
      QY(I)=DY
      QB(I)=SA
      X=XP-DX
      DA=-DX
      IF(X.GT.0.)GOTO 19
      DA=-XP
      SA=0.
      GOTD 20
      CALL GF(IN, SX, SY, X, XP, Y, YP, ZP, ZP, AA, BB, CC, SA)
19

```


20	UAA=DA*DA D1=SQR1(DAA+DYY) SA=SA-CM*COS(K*D1)/D1 J=I+3 QX(J)=DA QY(J)=DY QB(J)=SA SSS=SS+CD+CS*SD CS=CS+CD-SSS*SD ISUM=IXU+IXL+IYU+IYL IF(I SUM.EQ.0)GOTO 91 FO=0. DFY=0. DFXX=0. DFXY=0. DD 50 I=1,6 QA(I)=0. IF(IQD.EQ.2)GOTO 75 DX=AA-XP IF(DX.GE.XP)IXL=1 IF(DX.LE.XP)IXU=1 DX=XB-YP IF(DX.GE.YP)IYL=1 IF(DX.LE.YP)IYU=1 IF(IXU.EQ.0)GOTO 92 ISE=1 XS=2.*AA-XP GOTO 30 IF(IXL.EQ.0)GOTO 93 ISE=0 XS=-XP GOTO 30 IF(IYU.EQ.0)GOTO 94 ISE=1 YS=2.*BB-YP GOTO 40 IF(IYL.EQ.0)GOTO 95 ISE=0 YS=-YP GOTO 40 IF(IXU+IYU.NE.2)GOTO 96 ISE=-1 XS=2.*AA-XP YS=2.*BB-YP GOTO 60 IF(IXU+IYL.NE.2)GOTO 97
13	
50	
75	
92	
93	
94	
95	
96	

```

97 ISE=2.*AA-XP
   XS=-YP
   GOTD 60
   IF(IXL+IYU.NE.2)GOTO 98
   ISE=1
   XS=-XP
   YS=2.*BB-YP
   GOTD 60
   IF(IYL+IYL.NE.2)GOTO 99
   ISE=2
   XS=-XP
   YS=-YP
   GOTD 60
   D0 51 I=1,6
   QB(I)=QB(I)-QA(I)
   D1=QX(1)-QX(4)
   D2=QX(2)-QX(5)
   D3=QX(3)-QX(6)
   D4=QY(1)-QY(3)
   G7=(-QX(4)+QB(1))+QX(1)*QB(4))/D1
   G8=(-QX(6)+QB(3))+QX(3)*QB(6))/D3
   G0=.5*((-QX(4)+QB(1))+QX(1)*QB(4))/D4
   DGY=(G7-G8)/D4
   DGXY=((QB(1)-QB(4))/D1-(QB(3)-QB(6))/D3)/D4
   DGXX=2.*((QB(2)/QX(2)-QB(5)/QX(5))/D2+G0/QX(2)/QX(5))
   IF(I SUM.EQ.0)GOTO 53
   D0 52 I=1,6
   QB(I)=QB(I)+QA(I)
   G0=G0+FO
   DGY=DGY+DFY
   DGXX=DGXX+DFXX
   DGXY=DGXY+DFXY
   CHGF(IQD)=DGXX+KK*(G0+CQ)
   DGX(IQD)=DGY
   DGYX(IQD)=DGXY
   XP=YPP
   YP=XPP
   IT=IXU
   IXU=IYU
   IT=IT
   IYL=IYL
   SSS=AA
   AA=BB
   BB=SSS

```

99

51 91

52

53

49

14	RETURN Y=B8 DY=Y-YP DX=DEL DYY=DY*DY GOTO 16 Y=0. DY=-YP DX=DEL DYY=DY*DY GOTO 16 DO 31 I=1,6 DX=XP+QX(I)-XS DY=QY(I) R=SQRT(DX*DX+DY*DY) QA(I)=QA(I)-CM/R R=ABS(XP-XS) R3=R*R*R F0=F0-CM/R DFXX=DFXX-2.*CM/R3 IF(I SE)93,93,92 DO 41 I=1,6 DY=YP+QY(I)-YS DX=QX(I) R=SQRT(DX*DX+DY*DY) QA(I)=QA(I)+CM/R DY=YP-YS R=ABS(DY) R3=R*R*R F0=F0+CM/R DFY=DFY-CM*DY/R3 DFXX=DFXX-CM/R3 IF(I SE)95,95,94 DO 61 I=1,6 DX=XP+QX(I)-XS DY=YP+QY(I)-YS R=SQRT(DX*DX+DY*DY) QA(I)=QA(I)-CM/R DX=XP-XS DY=YP-YS DXX=DX*DX RR=DX*DY*DY R=SQRT(RR) R3=R*R*R R5=R3*RR F0=F0-CM/R DFY=DFY+CM*DY/R3
15	
30	
31	
40	
41	
60	
61	

```

DFXY=DFXY-3.*CM*DX*DY/R5
DFXX=DFXX+CM*(1./P3-3.*DX/R5)
IF(ISE)96,97,62
IF(ISE.EQ.1)GOTO 98
GOTO 99
PRINT 78
STOP
FORMAT(1X*WARNING--CAVITY DIMENSION TOO SMALL FOR DPLFIX*)
DX=X-XS
DY=Y-YS
ZZ=Z-Z1
ZZ1=ZZ1+Z1
R=SQR(ZZ+DX*DX+DY*DY)
SA=SA+CM/R
DX=X1-XS
DY=Y1-YS
R=SQR(ZZ1+DX*DX+DY*DY)
SB=SB+CM/R
IF(ISUM.EQ.1)GOTO 71
DX=X-XP
DY=Y-YS1
R=SQR(ZZ+DX*DX+DY*DY)
SA=SA+CM/R
DX=X1-XP
DY=Y1-YS1
R=SQR(ZZ1+DX*DX+DY*DY)
SB=SB+CM/R
DX=X1-XS
R=SQR(ZZ1+DX*DX+DY*DY)
SB=SB+CM/R
DX=X-XS
DY=Y-YS1
R=SQR(ZZ+DX*DX+DY*DY)
SA=SA+CM/R
IF(ISE)26,27,28
DX=XP-XS
DY=YP-YS
R=OX*DX+OY*DY
R=SQR(RR)
R3=R*RR
GAA=GAA-CM/R
DGAX=DGAX+CM*DX/R3
DGAY=DGAY+CM*DY/R3
DGMN=DGMN+CM/R3
IF(ISUM.EQ.1)GOTO 79
DY=YP-YS1
RR=DY*DY

```

62
77
78
70

71
72


```

RR1=RR+DX+DX
R=SQRT(RR1)
R3=R+RR1
GAA=GAA-CM/DY+CM/R
DGAX=DGAX-CM+DX/R3
DGAY=DGAY+CM/RR-CM+DY/R3
DGNN=DGNN-CM/R3+CM/RR/DY
GOTO 79
END

```

```

SUBROUTINE EAP(IN,SX,SY,E,N,FP,G1,G2,CON)
LOGICAL PHASAP
COMPLEX E,C2,CE
DIMENSION E(1),FP(1),G1(1),G2(1),IN(1),SX(1),SY(1)
DIMENSION LN(3),L(2,3),XA(2),RA(2),ALPH(2),EC(3),HC(3)
DIMENSION AN(3)
COMMON/DIPOLE/XP,YP,ZP,ALPE,ALPH,NWALL
COMMON/GRD/IGRD
COMMON/LAST/XA,NWAL
COMMON/LAST2/RA,EMAG,ANG,THE,PHI,PHASAP
COMMON/NEXTRA/N1,N2,N3
DATA LN,1,2,3/
DATA (LT(1),I=1,6)/2,3,3,1,1,2/
DATA AN/2HXX,2HY,2HZ/
DATA CE/10.,-376.7/
N1=N+1
N2=N+2
N3=N+3
NVAL=NWALL
NWHERE=8HORIZIN
IF(PHASAP)WHERE=8HAPERTURE
I1=LT(1,NWALL)
I2=LT(2,NWALL)
RX=0.
RY=0.
RZ=0.
NIN=NWALL-2
IF(NIN)1,2,3
XP=0.
YP=XA(1)
ZP=XA(2)
RY=RA(1)
RZ=RA(2)
GOTO 4
YP=0.

```

1

2

```

3      XP=XA(2)
      ZP=XA(1)
      RX=RA(2)
      RZ=RA(1)
      GOTO 4
      XP=XA(1)
      YP=XA(2)
      RX=RA(1)
      RY=RA(2)
      CALL ALPH (RA,ALPE,ALPM)
      PRINT 101,NWALL,XP,YP,ZP,RX,RY,RZ
      PRINT 103,ALPE,AN(I),ALPH(I),AN(I2),ALPH(2)
      PRINT 102,THE,PHI,EMAG,ANG,WHERE
      J=LN(NWALL)
      CALL EDIPL(J,FP,IN,SY,GI,G2,CON)
      DO 5 I=1,2
      J=LT(I,NWALL)
      IF(I.EQ.2) GOTO 6
      CALL MDIPL(J,GI,IN,SY)
      GOTO 5
      CALL MDIPL(J,G2,IN,SY)
      CONTINUE
      CALL INC(EMAG,ANG,THE,PHI,ET,EP,HT,HP,PHASE)
      CALL CONV(EC,ET,EP)
      CALL CONV(HC,HT,HP)
      J=LN(NWALL)
      C2=(1,0)
      IF(PHASAP) GOTO 8
      C2=C2+CEXP(0,1)*PHASE)
      DO 7 I=1,N
      E(I)=(0,0)
      E(N1)=2.*EC(J)*C2
      E(N2)=2.*HC(I1)*C2
      E(N3)=2.*HC(I2)*C2
      RETURN
      FORMAT(5X*APEPTURE LOCATION AND SIZE (WALL*I2*)*/
      10X*XA = *E10.3,5X*YA = *E10.3,5X*ZA = *E10.3/
      10X*RX = *E10.3,5X*RY = *E10.3,5X*RZ = *E10.3/
      *PHI) = (*E10.3*,*E10.3*)*/10X*WAVE IMPINGING FROM (THETA,*
      E10.3/10X*AND E-FIELD POLARIZATION ANGLE = *E10.3/10X
      *PHASE OF INCIDENCE POLARIZABILITIES:*/10X*ALPHA-E = *
      E10.3,5X*ALPHA-M*A2* = *E10.3,5X*ALPHA-M*A2* = *E10.3/
      END
101      1
102      2
103      1 2 3 1

```

```

SUBROUTINE INC(E,A,T,P,ET,EP,HT,HP,PH)
DIMENSION ALPHA(2)
COMMON/WN/K
COMMON/OVER/ST,CT,SP,CP
COMMON/DIPOLE/XP,YP,ZP,ALPE,ALPH,NWALL
REAL K
DATA PI/3.1415927/
RAD=PI/180.
RA=RAD*A
RT=RAD*T
RP=RAD*P
H=E/376.7
ET=-E+COS(RA)
EP=E*SIN(RA)
HT=H*SIN(RA)
HP=H*COS(RA)
ST=SIN(RT)
CT=COS(RT)
SP=SIN(RP)
CP=COS(RP)
PH=K*(XP*ST*CP+YP*ST*SP+ZP*CT)
RETURN
END

```

```

SUBROUTINE CONV(E,ET,EP)
DIMENSION E(1)
COMMON/OVER/ST,CT,SP,CP
E(1)=ET*CT*CP-EP*SP
E(2)=ET*CT*SP+EP*CP
E(3)=-ET*ST
RETURN
END

```

```

SUBROUTINE ALPHA(R,E,A)
REAL L
DIMENSION R(1),A(1)
DATA PI/3.1415927/
IF(R(2)-R(1))1,20,2
L=R(1)
W=R(2)
BIG=1
ISM=2
GOTO 3

```

1

```

2  L=R(2)
   W=R(1)
   IBIG=2
   X=(L-W)/L
3  IF(X.LT.1.E-3)GOTO 20
   RR=WT/LRAT
   EE=1.-RR
   CALL ELIPTIC(EE,FK,FE)
   CC=PI*LE*
   CC=CC*EE
   A(IIBIG)=CC/(FK-FE)
   A(IISR)=CC/(FE/RR-FK)
   E=C*RR/FE
   RETURN
20 L=R(1)
   E=2.*L*L/3.
   A(2)=2.*E
   A(1)=A(2)
   RETURN
END

```

20

44

```

SUBROUTINE ELIPTIC(X,EK,E)
DIMENSION A(4),B(4),C(4),D(4)
DATA A/.09666344259,.03590092383,.03742563713,.01451196212/
DATA B/.12498593597,.06880248576,.03328355346,.00441787012/
DATA C/.44325141463,.06260601220,.04757383546,.01736506451/
DATA D/.24998368310,.09200180037,.04069697526,.005226449639/
Y=1.-X
Z=ALOG(1./Y)
W=1.38629436112
P=1.5
Q=.1
R=1.
S=0.
DO 10 I=1,4
  W=W*Y
  P=P+A(I)*W
  Q=Q+B(I)*W
  R=R+C(I)*W
  S=S+D(I)*W
  EK=P+Q*Z
  E=R+S*Z
10

```

1

RETURN
END

SUBROUTINE MDIPL(J,E,IN, SX,SY)
DIMENSION E(1),IN(1),SX(1),SY(1),ALPH(2)
REAL K
COMMON/WN/K
COMMON/DIPOLE/XP,YP,ZP,ALPE,ALPH,NWALL
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
COMMON/FSUM/A,B,C,MAX
COMMON/GRD/IGRD
SD=0.
Z=7L
IF(IGRD.EQ.-1.OR.IGRD.EQ.2)Z=Z-DEL
XO=XC+R
DO 1 I=1,N
Z=Z+DEL
IF(J.EQ.3)GOTO 1
IF(J.EQ.2)GOTO 2
CALL GM(IN,SX,SY,XO,XP,YC,YP,Z,ZP,A,B,C,SD)
GOTO 1
CALL GM(IN,SX,SY,YC,YP,XO,XP,Z,ZP,B,A,C,SD)
SD=-SD
E(I)=SD
RETURN
END

2
1

SUBROUTINE EDIPL(J,E,IN, SX,SY,DUM,BUM,CON)
DIMENSION E(1),IN(1),SX(1),SY(1),DUM(1),BUM(1),ALPH(2)
REAL K
LOGICAL GEZ,ADYAD
COMMON/TYPE/ADYAD
COMMON/SPEC/GEZ
COMMON/WN/K
COMMON/DIPOLE/XP,YP,ZP,ALPE,ALPH,NWALL
COMMON/FORFILL/N,DEL,HDEL,ZL,XC,YC,R,CKD
COMMON/FSUM/A,B,C,MAX
COMMON/GRD/IGRD
Z=ZL
IF(IGRD.EQ.-1.OR.IGRD.EQ.2)Z=Z-DEL
CC=1./K
XO=XC+R
IF(J.EQ.3)GOTO 30

1	IF(ADYAD)GOTO 20
	DO 1 I=1,N
	Z=Z+DEL
20	IF(J.EQ.1)CALL GE(IN,SX,SY,XC,XP,YP,Z,ZP,A,B,C,SD)
	IF(J.EQ.2)CALL GE(IN,SX,SY,YC,YP,XD,XP,Z,ZP,A,B,C,SD)
	E(I)=CC*SD
	RETURN
	XD=XD+HDEL
	XH=XD-DEL
	YD=YD+HDEL
	YM=YD-DEL
	NP=N+1
	Z=ZL-HDEL
	CC=CC/DEL/DEL
	DO 2 I=1,NP
	Z=Z+DEL
	IF(J.EQ.2)GOTO 21
	CALL GA(IN,SX,SY,YP,Z,ZP,XD,XP,B,C,A,SD)
	CALL GA(IN,SX,SY,YP,Z,ZP,XH,XP,B,C,A,SH)
21	GOTO 22
22	CALL GA(IN,SX,SY,Z,ZP,XD,XP,YD,YP,C,A,B,SD)
2	CALL GA(IN,SX,SY,Z,ZP,XD,XP,YH,YP,C,A,B,SH)
	DUM(I)=SD
	BUM(I)=SH
	DO 3 I=1,N
3	IP=I+1
	E(I)=CC*(DUM(IP)-BUM(IP)-DUM(I)+BUM(I))
	RETURN
25	NP=N+2
	Z=ZL-DEL
	CC=K/CON
	DO 4 I=1,NP
	Z=Z+DEL
4	CALL GA(IN,SX,SY,XD,XP,YP,Z,ZP,A,B,C,SD)
	DUM(I)=SD
5	DO 5 I=1,N
	E(I)=CC*(DUM(I)+DUM(I+2)-CKD*DUM(I+1))
	RETURN
30	IF(ADYAD)GOTO 25
	GEZ=.T.
	DO 6 I=1,N
	Z=Z+DEL
6	CALL GA(IN,SX,SY,XD,XP,YP,Z,ZP,A,B,C,SD)
	E(I)=CC*SD
	GEZ=.F.
	RETURN
	END

```

FUNCTION S3(Z,ZP,W,WP,C,D)
COMMON/PEEK/I
COMMON/SUMS/KK,N,CONV,LC
REAL KK,KW,KC,KWW
DATA PI/3.1415927/
X=PI/D
KW=0.
ZL=MIN1(Z,ZP)
ZG=C-AMAX1(Z,ZP)
ARG=X*(C-ZG-ZL)
CX=COSH(ARG)
SUM=
1 .125*ALOG((CX-COS(X*(W+WP)))/(CX-COS(X*(W-WP))))/X
L=0
DO 1 I=1,N
KW=KW+X
KWW=KW*KW
SKC=KK-KWW
IF(KWW.GT.KK)GOTO 2
KC=SQR(SKC)
T=SIN (KC*ZL)*SIN (KC*ZG)/SIN (KC*C)/KC
GOTO 3
KC=SQR(T*(-SKC))
T=SINH(KC*ZL)*SINH(KC*ZG)/SINH(KC*C)/KC
IT=SIN(KW*W)*SIN(KW*WP)*(T-.5*EXP(-I*ARG))/KW)
SUM=SUM+IT
L=L+1
AB=ABS(TT/SUM)
IF(AB.GT.CONV)L=0
IF(L.EQ.LC) GOTO 4
CONTINUE
PRINT 5,AB,L
STOP
S3=SUM*2./D
FORMAT(10X*WARNING--SUM 3 NOT CONVERGED*E15.5I10)
RETURN
END

SUBROUTINE GM(IN,SX,SY,X,XP,Y,YP,Z,ZP,A,B,C,SD)
DIMENSION IN(1),SX(1),SY(1)
COMMON /NEUMAN/ MO,NO
COMMON /GM/ MAX
LGM=-1
IF(Y.GT.YP)GOTO 5
AS=Y

```

5	SIG=-1. AC=B-YP GOTO 6 AS=B-Y AC=YP SIG=1. GOTO 6 ENTRY GA LGM=0 GOTO 6 ENTRY GF LGM=1 NO=1 MO=NO DX=X-YP DY=Y-YP DZ=Z-ZP RA=1./A/A RB=1./B/B RC=1./C/C ALP=(RB+RC)*DX+DX BET=(RA+RB)*DZ+DZ GAM=(ALP+BET)*GT IF(BET.GT.GAM)GOTO 10 GOTO 3 IF(ALP.LE.GAM)GOTO 3 IF(B.GT.C)GOTO 4 NAX=C*MAX/B NG=0 IF(LGM.EQ.1)MO=0 CALL NDE(SX,Y,YP,B,MAX,LGM) CALL NCC(SY,Z,ZP,C,NAX) CALL GHI(IN,SX,SY,X,XP,B,C,A,SD) RETURN NAX=B*MAX/C MO=0 IF(LGM.EQ.1)NO=0 CALL NDE(SY,Y,YP,B,NAX,LGM) CALL NCC(SX,Z,ZP,C,MAX) CALL GHI(IN,SX,SY,X,XP,C,B,A,SD) RETURN IF(A.GT.C)GOTO 7 NAX=C*MAX/A NO=0 CALL NSS(SX,X,XP,A,MAX) CALL NCC(SY,Z,ZP,C,NAX)
6	
10 1	
4	
2	


```

11 IF(LGM)12,11,21
    CALL GH1(IN,SX,SY,Y,YP,A,C,B,SD)
    GOTO 13
21 CALL GH3(IN,SX,SY,Y,YP,A,C,B,SD)
    GOTO 13
12 CALL GH2(IN,SX,SY,AS,AC,A,C,B,SD)
    SD=SIG*SD
    RETURN
13 MAX=A*MAX/C
    MO=0
    CALL NSS(SY,X,XP,A,NAX)
    CALL NCC(SX,Z,ZP,C,MAX)
    IF(LGM)15,14,22
14 CALL GH1(IN,SX,SY,Y,YP,C,A,B,SD)
    GOTO 13
22 CALL GH3(IN,SX,SY,Y,YP,C,A,B,SD)
    GOTO 13
15 CALL GH2(IN,SX,SY,AS,AC,A,C,B,SD)
    SD=SIG*SD
    RETURN
3 IF(A.GT.8)GOTO 8
    NAX=8*MAX/A
    IF(LGM.EQ.1)MO=0
    CALL NSS(SX,X,XP,A,MAX)
    CALL NDE(SY,Y,YP,B,NAX,LGM)
    CALL GH3(IN,SX,SY,Z,ZP,A,B,C,SD)
    RETURN
8 NAX=A*MAX/8
    IF(LGM.EQ.0)MO=0
    CALL NSS(SY,X,XP,A,NAX)
    CALL NDE(SX,Y,YP,B,MAX,LGM)
    CALL GH3(IN,SX,SY,Z,ZP,B,A,C,SD)
    RETURN
    END

SUBROUTINE GE(IN,SX,SY,X,XP,Y,YP,Z,ZP,A,B,C,SD)
DIMENSION IH(1),SX(1),SY(1)
COMMON /NEUMAN/ MO,NO
CGMNON /GM/ MAX
MO=1
NO=1
SIG=1
DX=X-XP
DY=Y-YP
DZ=Z-ZP

```

10	RA=1./A/A
1	RB=1./B/B
	RC=1./C/C
	ALP=(RB+RC)*DX*DX
	BET=(RA+RB)*DY*DY
	GAM=(RA+RB)*DZ*DZ
	IF(ALP.GT.BET)GOTO 10
	IF(BET.GT.GAM)GOTO 2
	GOTO 3
	IF(ALP.LE.GAM)GOTO 3
	IF(X.GT.XP)GOTO 12
	AC=A-XP
	AS=X
	SIG=-1.
	GOTO 11
12	AC=XP
11	IF(B.GT.C)GOTO 4
	NAX=C*MAX/B
	CALL NSS(SX,Y,YP,B,MAX)
	CALL NSC(SX,ZP,Z,C,MAX)
	CALL GM2(IN,SX,SY,AS,AC,B,C,A,SD)
	SD=SIG*SD
	GOTO 6
4	NAX=B*MAX/C
	CALL NSS(SX,Y,YP,B,MAX)
	CALL NSC(SX,ZP,Z,C,MAX)
	CALL GM2(IN,SX,SY,AS,AC,C,B,A,SD)
	SD=SIG*SD
	GOTO 6
2	IF(A.GT.C)GOTO 7
	NAX=C*MAX/A
	CALL NSC(SX,X,XP,A,MAX)
	CALL NSC(SX,ZP,Z,C,MAX)
	CALL GM1(IN,SX,SY,Y,YP,A,C,B,SD)
	GOTO 6
7	NAX=A*MAX/C
	CALL NSC(SX,X,XP,A,MAX)
	CALL NSC(SX,ZP,Z,C,MAX)
	CALL GM1(IN,SX,SY,Y,YP,C,A,B,SD)
	GOTO 6
3	IF(Z.GT.ZP)GOTO 5
	AC=Z-ZP
	AS=C-ZP
	GOTO 13
5	AC=C-Z
	AS=ZP

```

13      SIG=-1
      IF(A.GT.B)GOTO 8
      NAX=B*MAX/A
      CALL NSC(SX,X,XP,A,MAX)
      CALL NSS(SY,Y,YP,B,MAX)
      CALL GM2(IN,SX,SY,AS,AC,A,B,C,SD)
      SD=SIG*SD
      GOTO 6
8      NAX=A*MAX/B
      CALL NSC(SX,X,XP,A,MAX)
      CALL NSS(SY,Y,YP,B,MAX)
      CALL GM2(IN,SX,SY,AS,AC,A,B,C,SD)
      SD=-SD
      RETURN
      END
6

```

```

SUBROUTINE BADSUM(IN,SX,SY,X,SD)
REAL K,KK,KX
DIMENSION IN(1),SX(1),PX(1),SY(1)
LOGICAL CIND
COMMON/YES/CIND
COMMON/WN/K
COMMON/PEEK/M
COMMON/FSUM/A,B,C,MAX
COMMON/SUMS/KK,NSH,CONV,LC
DATA PI/3.1415927/
AR=PI/A
BR=PI/B

```

```

10      L=0
      SBR=BR*BR
      CW=C-X
      DO 10 M=1,MAX
      IN(M)=0
      SUM=0
      DO 1 M=1,MAX
      KX=M*AR
      SKX=KX*KX
      RR=SKX+SBR
      IN(M)=1
      SUM=SUM+RR
      I=M
      N=1
      GOTO 9
      I=I-1
      IF(I.EQ.0)GOTO 7

```

```

        KX=I*AR
        SKX=KX*KX
        NF=IN(1)+1
        IN(1)=SQRT((RR-SKX)/BR
        NL=IN(1)
        IF(NF.GT.NL)GOTO 2
        DO 3 N=NF,NL
            GOTO 9
        CONTINUE
        GOTO 2
        BSUM=BSUM+SUM
        L=L+1
        AB=ABS(SUM/BSUM)
        IF(AB.GT.CONV)L=0
        IF(L.EQ.LC)GOTO 4
        CONTINUE
        CIND=.T.
        RETURN
        SKY=N*N+SBR-KK
        SGC=SKY+SKX-KK
        IF(SGC.GT.0.)GOTO 11
        GC=SQRT(-SGC)
        T=SIN(GC*CW)/SIN(GC*C)
        GOTO 12
        GC=SQRT(SGC)
        T=RSINH(GC*CW,GC*C)
        TT=T*SX(1)*SY(N)/SGC
        SUM=SUM+TT
        IF(1.EQ.M)GOTO 2
        GOTO 6
        SD=-BSUM*2./A/B
        RETURN
        END

```

6 3

7

1

9

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4

```

SUBROUTINE GM1(IN,SX,SY,Z,P,A,B,C,SD)
    REAL K,KK,KXX,KXX
    LOGICAL GEZ
    DIMENSION IN(1),SX(1),SY(1)
    COMMON /WN/K
    COMMON /PEEK/M
    COMMON /NEUMAN/MO,NO
    COMMON /GH/MAX
    COMMON /SUMS/KK,NSM,CONV,LC
    COMMON /SPEC/GEZ

```



```

DATA PI/3.1415927/
IND=1
GOTO 55
ENTRY GM3
IND=3
ZL=AMIN1(Z,ZP)
ZG=C-AMAX1(Z,ZP)
GOTO 8
ENTRY GM2
IND=2
AC=ZP
AS=Z
INDH=IND-2
AR=PI/A
BR=PI/B
L=0
SBR=BR*BR
DO 10 M=1,MAX
IN(M)=0
BSUM=0.
KXX=MO*AK
NN=1-NO
DO 1 M=1,MAX
KX=KXX
SKX=KX*KX
RR=SKX+NO*SBR
IN(M)=NO
SUM=0.
I=M
N=NO
GOTO 9
I=I-1
IF(I.EQ.0)GOTO7
KX=KX-AR
SKX=KX*KX
NF=IN(I)+1
IN(I)=SQRT(RR-SKX)/BR
NL=IN(I)
IF(NF.GT.NL)GOTO 2
DO 3 N=NF,NL
GOTO 9
CONTINUE
GOTO 2
BSUM=BSUM+SUM
L=L+1
AB=ABS(SUM/BSUM)

```

55

8

10

2

6

3

7

```

1      IF(AB.GT.CONV)L=0
      IF(L.EQ.LC)GOTO 4
      KXX=KXX+AR
      PRINT 5,IND,AB,L
      STOP
9      SKY=N*N*SBR
      SKC=SKY+SKX
      SGC=SKC-KK
      IF(SGC.GT.0.)GOTO 11
      GC=SQRT(-SGC)
13     IF(INDM)13,14,15
      T=SIN(GC*ZL)*SIN(GC*ZG)/SIN(GC*C)/GC
      GOTO 12
14     T=COS(GC*AC)*SIN(GC*AS)/SIN(GC*C)
      GOTO 12
15     T=-COS(GC*ZL)*CDS(GC*ZG)/SIN(GC*C)/GC
      IF(GEZ)T=T*SKC
      GOTO 12
11     GC=SQRT(SGC)
      IF(INDM)16,17,18
16     T=RSS(GC*ZL,GC*ZG,GC*C)/GC
      GOTO 12
17     T=RCS(GC*AC,GC*AS,GC*C)
      GOTO 12
18     T=RCC(GC*ZL,GC*ZG,GC*C)/GC
      IF(GEZ)T=T*SKC
12     TT=T*SX(I)*SY(N+NN)
      IF(N.EQ.0) TT=.5*TT
      IF(MO+I.EQ.1) TT=.5*TT
      SUM=SUM+TT
      IF(I.EQ.M)GOTO 2
      GOTO 6
4      SD=4.*BSUM/A/B
5      FORMAT(10X*WARNING--GM*11* SUM NOT CONVERGED*E15.5I10)
      RETURN
      END

```

```

SUBROUTINE NSS(D,X,XP,A,M)
  DIMENSION D(1)
  DATA PI/3.1415927/
  AR=PI/A
  W=0.
  DO 1 I=1,M
    W=W+AR
  D(I)=SIN(W*X)*SIN(W*XP)

```

RETURN
END

```

SUBROUTINE NCC(D,Z,ZP,C,M)
  REAL KK
  LOGICAL GEZ
  COMMON/SUMS/KK,NSM,CONV,LC
  DIMENSION D(1)
  DATA PI/3.1415927/
  AR=PI/C
  D(1)=1.
  W=0.
  DO 1 I=1,M
    W=W+AR
    IP=I+1
    D(IP)=COS(W+Z)*COS(W+ZP)
    IF(GEZ) D(IP)=D(IP)*(KK-W*W)
  CONTINUE
  IF(GEZ) D(1)=KK
  RETURN
END

```

1

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```

SUBROUTINE NSC(D,YS,YC,B,M)
  DIMENSION D(1)
  DATA PI/3.1415927/
  AR=PI/B
  W=0.
  DO 1 I=1,M
    W=W+AR
    D(I)=W*SIN(W*YS)*COS(W*YC)
  RETURN
END

```

1

```

SUBROUTINE NDE(D,Y,YP,B,M,L)
  DIMENSION D(1)
  IF(L1,2,3)
    CALL NSC(D,Y,YP,B,M)
  RETURN
  CALL NSS(D,Y,YP,B,M)
  RETURN

```

1

2

```

3      CALL NCC(D,Y,YP,B,M)
      RETURN
      END

      FUNCTION COSH(X)
      Y=EXP(X)
      COSH=.5*(Y+1./Y)
      RETURN
      END

      FUNCTION SINH(X)
      Y=EXP(X)
      SINH=.5*(Y-1./Y)
      RETURN
      END

      FUNCTION RSS(X,Y,Z)
      RSS=.5*(EXP(X+Y-Z)-EXP(X-Y-Z)-EXP(Y-X-Z)+EXP(-X-Y-Z))
      1 / (1.-EXP(-Z-Z))
      RETURN
      END

      FUNCTION KCC(X,Y,Z)
      RCC=.5*(EXP(X+Y-Z)+EXP(X-Y-Z)+EXP(Y-X-Z)+EXP(-X-Y-Z))
      1 / (1.-EXP(-Z-Z))
      RETURN
      END

      FUNCTION RCS(X,Y,Z)
      RCS=.5*(EXP(X+Y-Z)-EXP(X-Y-Z)+EXP(Y-X-Z)-EXP(-X-Y-Z))
      1 / (1.-EXP(-Z-Z))
      RETURN
      END

```



```
FUNCTION RSINH(X,Y)
  RSINH=(EXP(X-Y)-EXP(-X-Y))/(1.-EXP(-Y-Y))
  RETURN
END
```